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Creating Wallonia's new
very high resolution land cover maps:
combining GRASS GIS OBIA
and OTB pixel-based results

FOSS4G-BE 2019

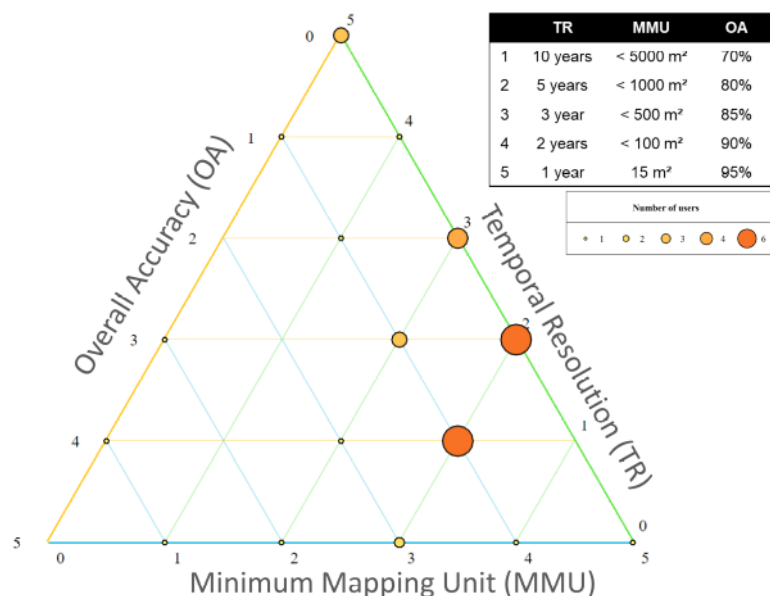
M. Lennert, T. Grippa, J. Radoux, C. Bassine, B. Beaumont, P. Defourny, E. Wolff

*The authors would like to acknowledge the Walloon Government for the funding
of the project WALOUS.*

Context : Project

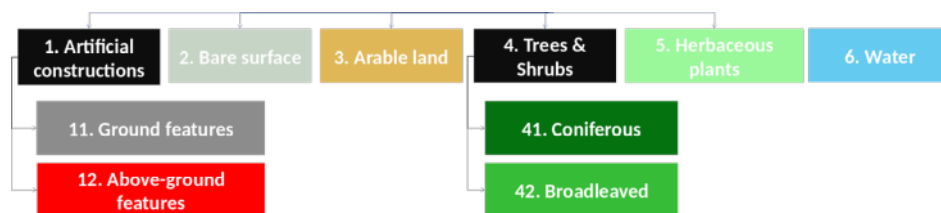
- Need for new land cover and land use maps of Wallonia
- Desire of the administration to obtain not only products, but methods
- Method should be open, reproducible and easily understandable by the administration
- Different existing research projects of the participating universities provided elements of methods
- Results have to be compliant both with user needs and with EU INSPIRE directive

Objectives

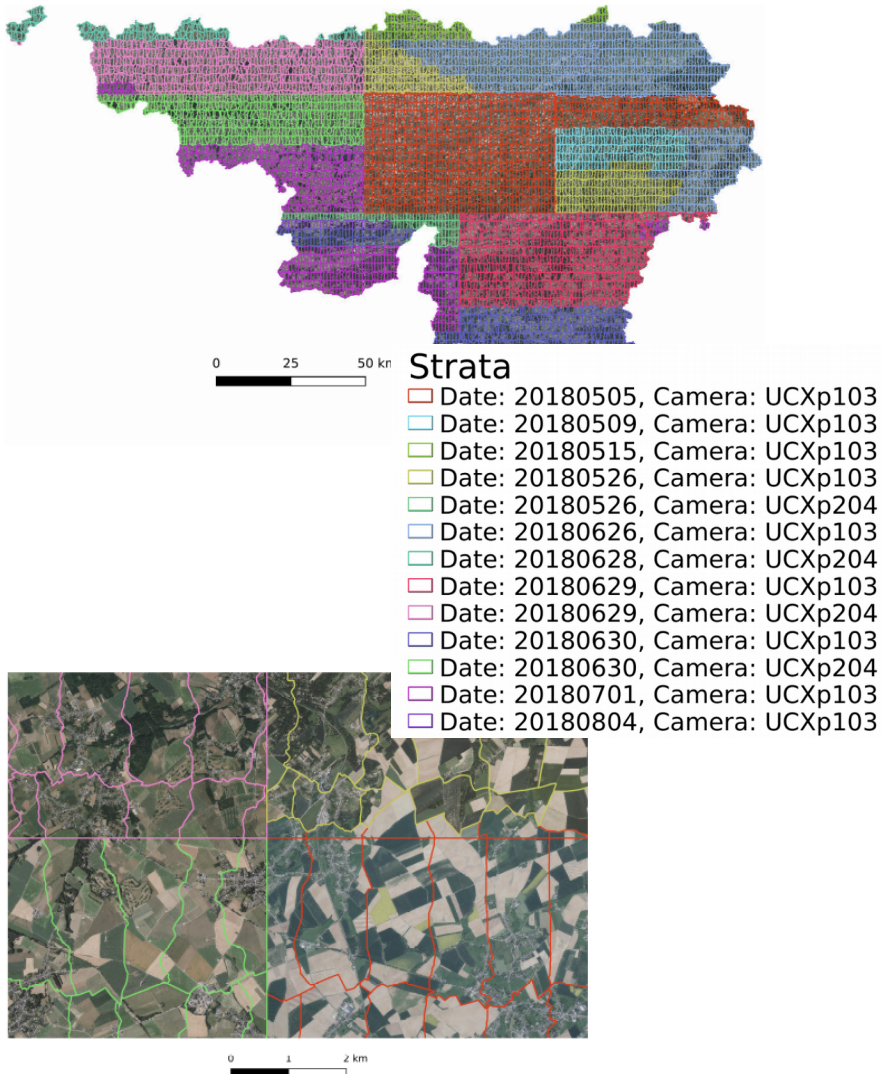


Compromises between objectives as preferred by users

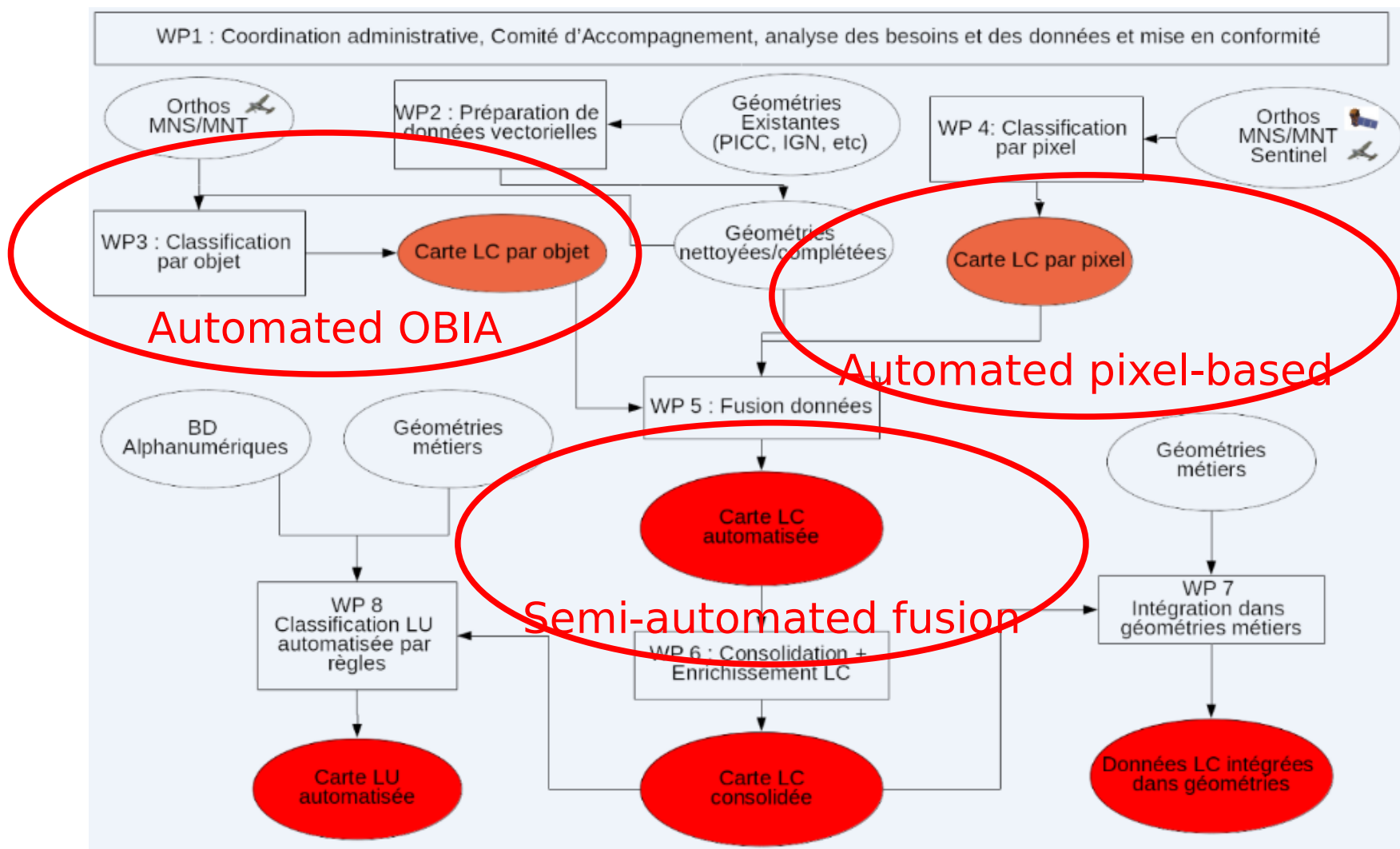
- Intense interaction with potential users to define needs and specifications
- Work on defining :
 - Legend
 - Temporal resolution
 - Overall accuracy threshold
 - Minimum mapping unit
- Current results of process :
 - OA : 85 %
 - MMU : 15m2
 - Update frequency : 3-5 years



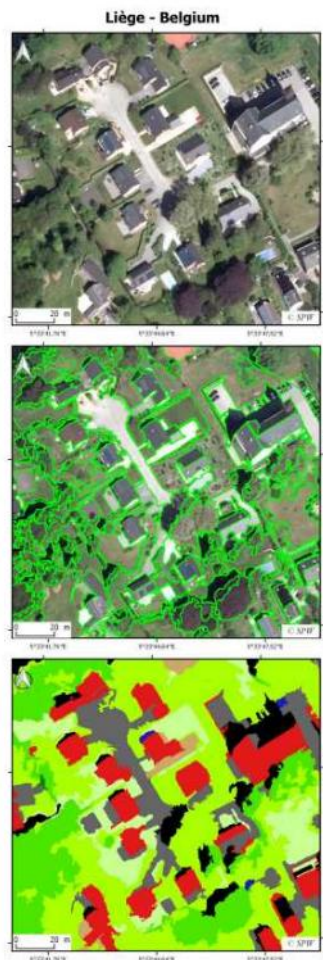
Proposed land cover legend



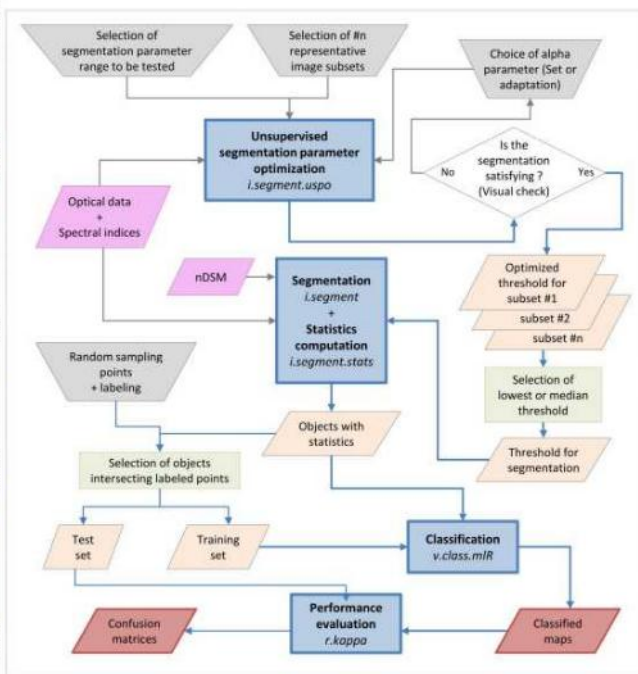
- 25cm orthophotos (RGB + NIR)
 - 2018
 - photomosaic from images taken during different flights
 - stratification by different dates and cameras
- nDSM (height layer) derived from the orthophotos
- Auxiliary vector data (buildings, roads, waterways, forests, agricultural fields)
 - Not always up to date
 - Not easily usable (e.g. roads only as axes, not polygons)
- Total size of dataset ~ 2.5TB



Method : OBIA



AN OPEN-SOURCE
SEMI-AUTOMATED PROCESSING CHAIN
FOR URBAN OBJECT-BASED CLASSIFICATION

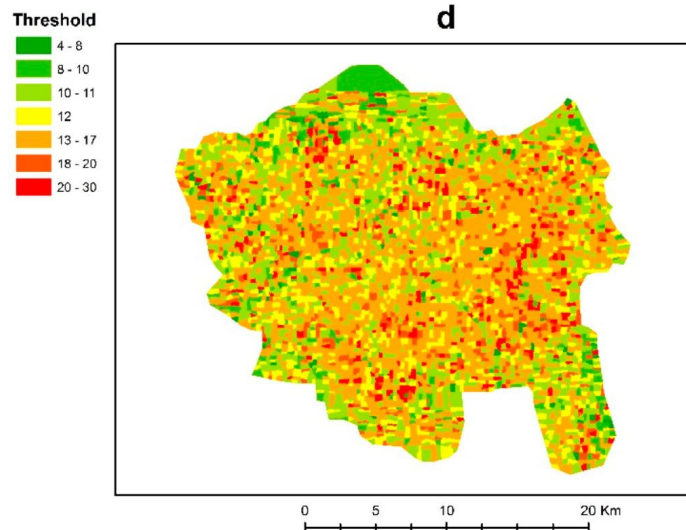


source : Grippa et al (2017), Remote Sensing,
<https://dx.doi.org/10.3390/rs9040358>

- GRASS GIS
- Scripts using GRASS GIS Python API
- R for machine learning classifier
- HPC application (shared ICT Services Centre, Université Libre de Bruxelles) : highly parallelized

Method : OBIA

Spatial variation of
« optimal »
segmentation
parameter



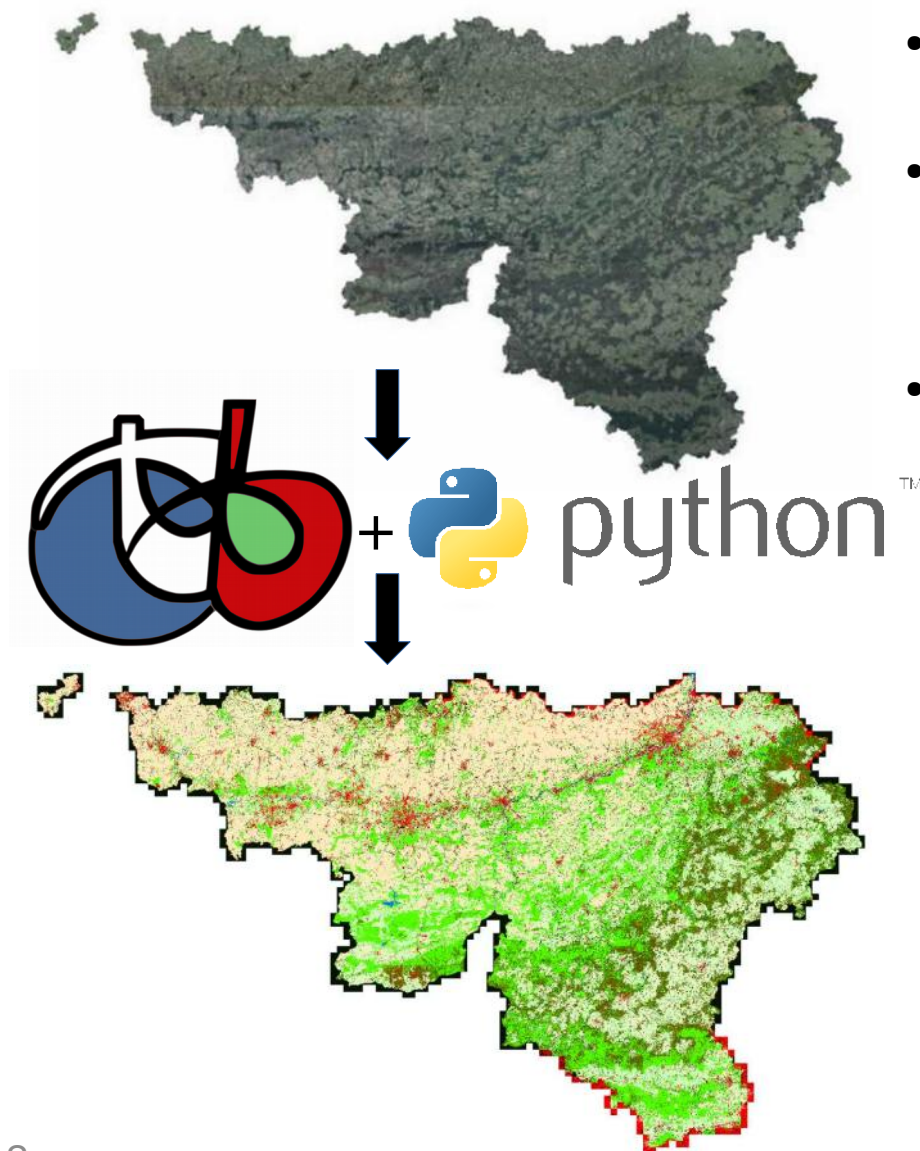
Cutlines



- Cutlines for tile creation (*i.cutlines*)
- Superpixels for acceleration (*i.superpixels.slic*)
- Spatially partitioned unsupervised parameter optimisation (*i.segment.uspo*)
- Automatic selection of training objects based on existing databases
- Random forest classifier (*v.class.mlr*)

source : Georganos et al (2018), Remote Sensing,
<https://doi.org/10.3390/rs10091440>

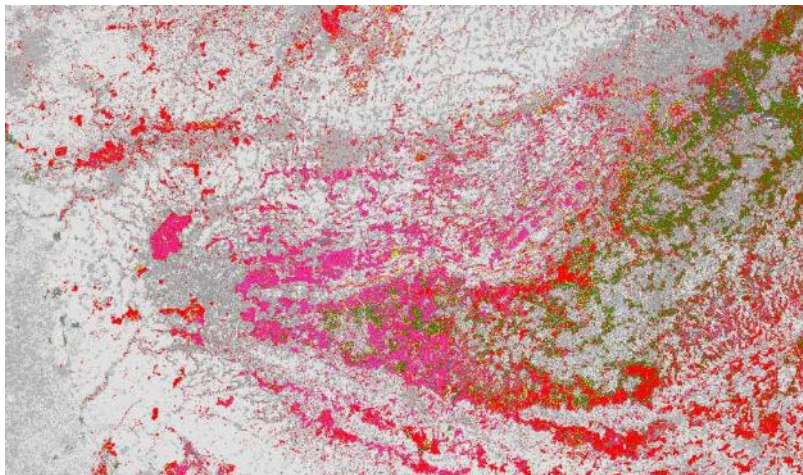
Method : Pixel-based



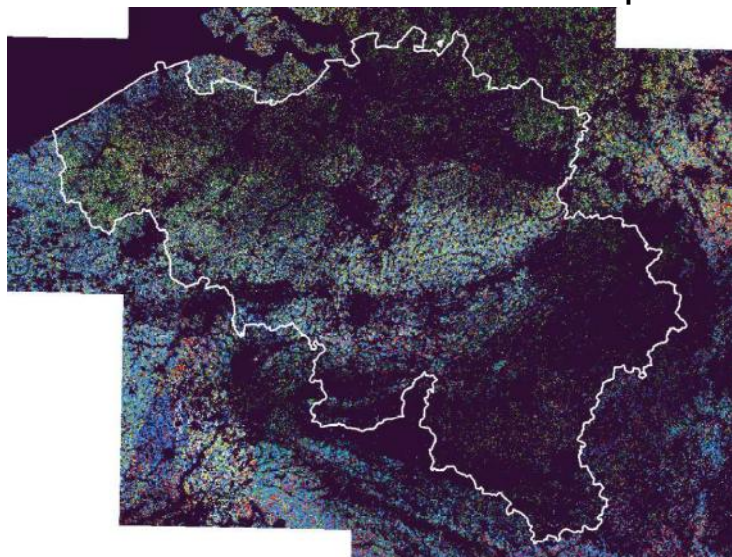
- One main product based on the 25 cm orthophotos + nDSM
- Tools
 - Orfeo ToolBox (OTB) + Python
 - HPC (CÉCI, F.R.S.-FNRS Grant No. 2.5020.11 and Walloon Region)
- Main steps
 - Mean shift smoothing (Comaniciu and Meer 2002)
 - Reference dataset compiled from existing 2m LC map, nDSM and shadows derived from nDSM
 - Reference dataset eroded using multiclass mathematical morphology operator (Radoux et al. 2014).
 - Classification with height as a priori probability

Method : Pixel-based

Sentinel-2, Forest classification

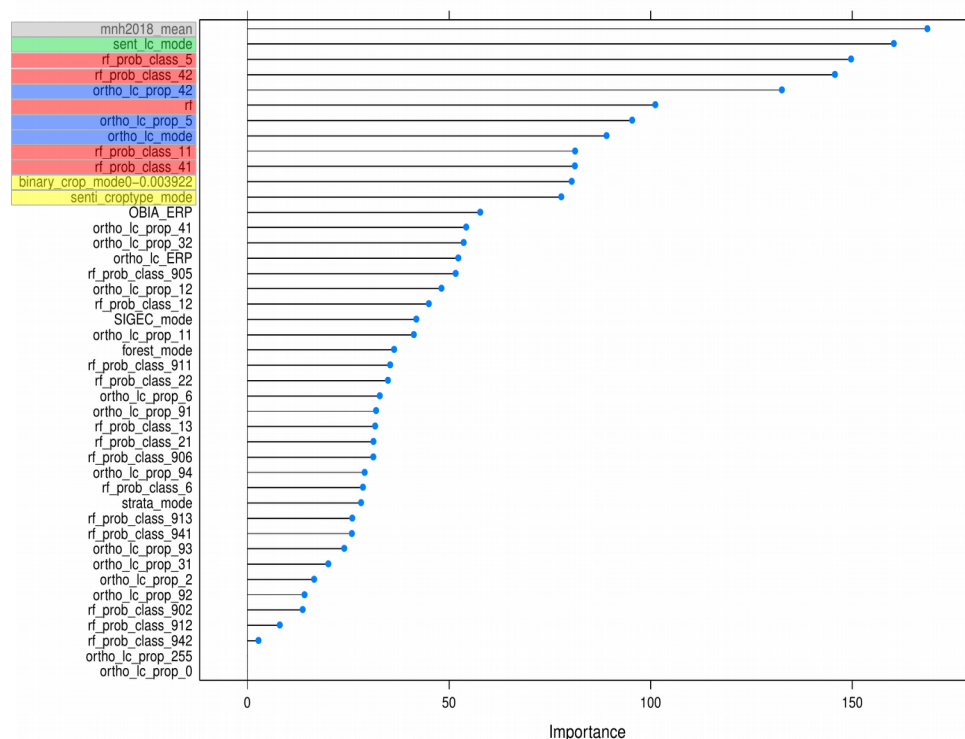


SEN2AGRI : black = no crops



- Other pixel-based layers using Sentinel-2 :
 - Landcover based on two dates allowing discrimination of vegetation (e.g. deciduous vs coniferous)
 - Multitemporal SEN2AGRI toolbox product (<http://www.esa-sen2agri.org/>) for crop identification

Method : Fusion

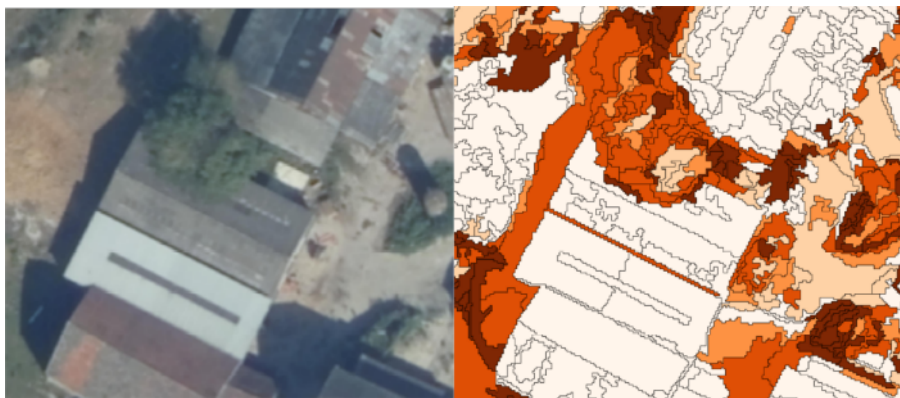


Final automated classification

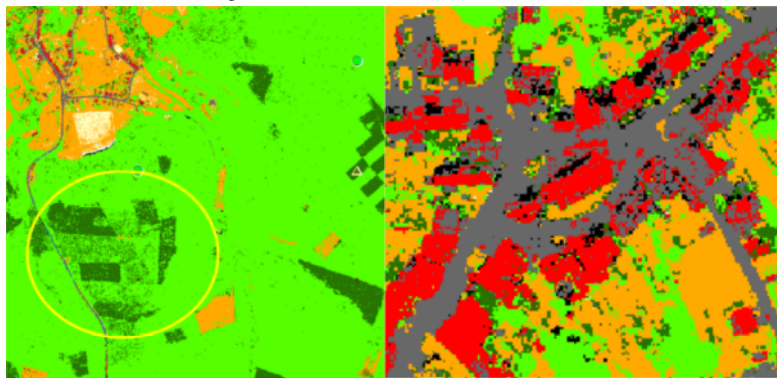
- Combine strengths of each method
- Input :
 - Classes and class probabilities
 - Some auxiliary data
- Test of three methods
 - Pixel-based
 - Rule-based (as benchmark, but difficult to generalize)
 - Dempster-Shafer
 - Object-based :
 - Machine learning (Random Forest)

Results : Classification

OBIA : Sharp building edges, but
over-segmentation for vegetation
=> higher uncertainty (darker color)



Per pixel : Salt-and-pepper effect
and object delineation issues



- Each classification has its strengths...
 - OBIA : shapes of objects (e.g. urban) + smoothness
 - Per-pixel : vegetation
- ... but also weaknesses :
 - OBIA : oversegmentation for vegetation
 - Per-pixel : salt-and-pepper effect, object delineation

Results : Fusion

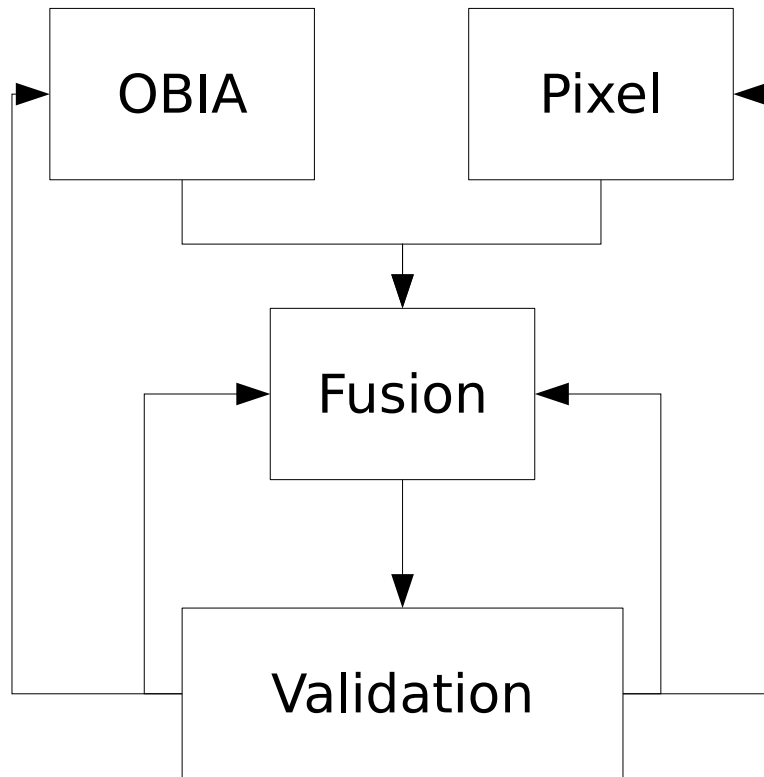


Object-based



Dempster-Shafer

- Fusion methods :
 - Object-based :
 - smoother with sharp edges
 - Dempster-Shafer :
 - difficulties with multiple resolutions
 - thematically sometimes better
- Difficulty with class « arable land » :
 - Multitemporal from Sentinel, so only available at 10m resolution
- Semi-automated approach
OA : 0.87 (8 classes)
 - Will be improved with manual consolidation



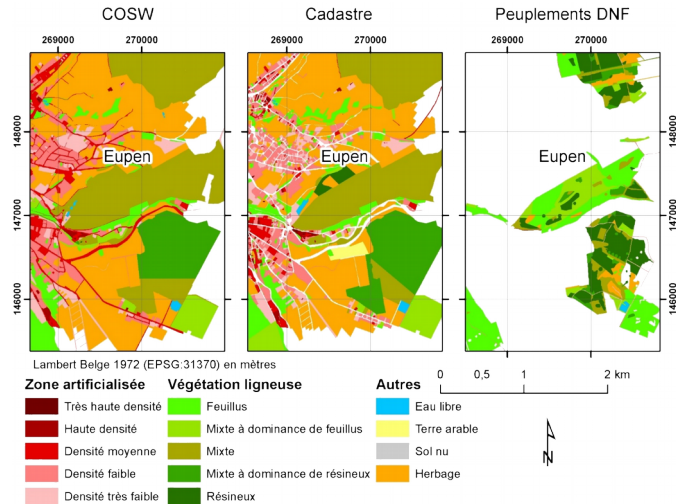
- Fusion provides qualitative improvement over individual classifications
- Object-based, machine learning approach seems most efficient
- Accuracy of the inputs into the fusion is major determinant of the quality of results
- => Iterative approach : back and forth between fusion and original classifications



- Project has contributed to the development of FOSS tools
- A general heavy-duty real-life test of the GRASS GIS OBIA pipeline
- Enhancement of existing modules :
 - i.segment.uspo
 - i.segment.stats
 - i.cutlines
 - v.class.mlr
 - etc
- Development of new modules :
 - r.texture.tiled

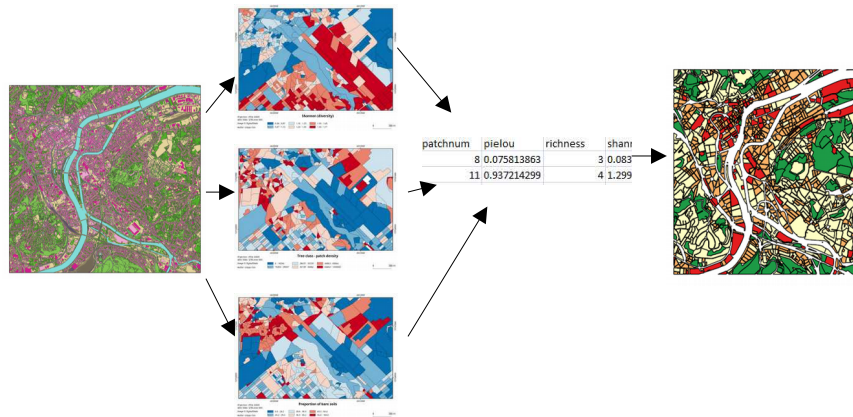
OBIA HPC scripts available on github :
<https://github.com/mlennert/WALOUS>

Land cover aggregated in domain-specific polygons



- Finalization of entire automated approach
- Manual correction of land cover map => very high quality product
- Integrate LC information into
 - Domain-specific polygons
 - Automated process for land use mapping
- Products should be available as open data
- Future work :
 - Updating methodology
 - Use results as input for deep learning approach

From land cover-based landscape metrics to land use



Thank you for your attention!!!

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